

LOCAL DYNAMIC MAP

Aim: to represent the vehicle's surroundings with all static and dynamic safety-relevant elements

Output of cooperative sensing/processing

Temporary regional info

Landmarks for referencing

Map from provider

Legacy vehicle

Vehicles in queue

Signaling phases

Own Vehicle – position, direction, speed, status, etc

Slippery road surface (ice)

Tall Tree

Fog bank

Accident (just occurred)

